

# Holonomic quantum control via nonlinear realizations

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September 20, 2021

## Abstract

Geometric phases appear as holonomies in principal bundles over quantum state spaces. In this work, we consider the case when the principal bundle itself is a Lie group and the quantum space of states a homogeneous space of that group. This structure allows the application of the theory of nonlinear realizations of symmetry for the construction non-Abelian geometric phases corresponding to this bundle structure. When the quantum state space is the complex Grassmann manifold  $U(N)/(U(N-k) \times U(k))$ , we identify the total non-Abelian Aharonov-Anandan phase as the  $U(k)$ -valued cocycle of the  $U(N)$  action on the Grassmann manifold. We describe generalizations of this result in two cases: 1) the case of isospectral dynamics of mixed states, 2) the case of non-self adjoint dynamics over the Grassmannian.

## Introduction

### Holonomic quantum control on Lie group total space principal bundles

In this work, we describe a geometric setup for holonomic quantum control on principal bundles. We treat a particular case in which our control system is a principal bundle whose total space is a Lie group  $G$ , and the bundle projection is the canonical projection onto an appropriately chosen coset space  $G/H$  with respect to a closed subgroup  $H$ . The group  $G$  and the subgroup  $H$  will be chosen such that base space of the bundle becomes a space of quantum states. The control system's role, in this setup, is to generate, by holonomy, a group action on a physical system having a similar structure of a Lie group total space principal bundle.

The Lie group bundle structure allows a special connection: the  $H$ -connection, whose holonomy along a closed path on the space of quantum states is the non-Abelian geometric phase which will be used to drive the physical system. This setup in which the bundle is a Lie group, allows the use of the theory of nonlinear realizations for the construction of the  $H$ -connection and the holonomy.

We put the holonomy into action, through a bundle map to a physical system, having also the same structure of a Lie group total space principal bundle space but with different isotropy group  $K \subset H$ :

$$\begin{array}{ccc}
\begin{array}{c} H \\ i_{HG} \downarrow \\ G \\ \pi_{HG} \downarrow \\ G/H \end{array} & \cong & \begin{array}{c} K \\ i_{KG} \downarrow \\ G \\ \pi_{KG} \downarrow \\ G/K \end{array} \\
\text{Control System} & & \text{Physical System}
\end{array}
=
\begin{array}{c} K \\ i_{KH} \downarrow \\ H \\ \pi_{KH} \downarrow \\ H/K \end{array}$$

The control system simulates a closed path on the base space  $G/H$  which is a projection of a generally open path on the total space of the principal bundle:  $H \xrightarrow{i_{HG}} G \xrightarrow{\pi_{HG}} G/H$  due to the existence of a nontrivial holonomy. This holonomy drives our physical system through a bundle map to a second version of the same Lie group  $G$ , this time belonging to our physical system. The initial state of the physical system is chosen so that the isotropy group of the action is now  $K$  a subgroup of  $H$ . In this geometric setup, the physical state space  $G/K$  becomes a fibre bundle over the control system base space  $G/H$  with a fibre isomorphic to  $H/K$ , when the control system completes one revolution, the physical system will return to the starting point on the base space of this bundle, but in general will end up in a different point on the fibre  $H/K$  than the starting point, thus the physical state space is actually encoded in the fibre of this bundle.

This formulation consists of a slightly different approach than [1]. The bundle map from the control system to the physical system is similar

## Nonlinear realizations

When a Lie group acts on a manifold without a global linear structure, its action defines a nonlinear representation or a nonlinear realization. Nonlinear realizations can be explicitly constructed when the manifold is a homogeneous space of the Lie group. The name: *Nonlinear realization* was coined (at least in the physics literature) by Wess and Zumino [2] and Weinberg [3] for the case of chiral symmetry groups. It was generalized to arbitrary compact Lie groups in the classic papers of Callan Coleman Wess and Zumino (CCWZ) [4] and [5] for the study of the dynamics of the Nambu-Goldstone bosons in systems with spontaneous symmetry breaking. The configuration space of the Nambu-Goldstone bosons at very low energies becomes a homogeneous space of the symmetry group  $G$  of the theory, with the symmetry group  $H$  of the vacuum acting as the isotropy group.

The method of nonlinear realizations was extended to Kählerian homogeneous spaces, which appear as the low energy configuration spaces of spontaneously broken supersymmetric theories, by Bando, Kuratomo, Maskawa and Uehara (BKMU) [6] and [7]. Compact Kählerian homogeneous spaces allow complex non-compact transitive group actions, which can be used to model non-self adjoint dynamics. Non-compact Kählerian homogeneous spaces allow in addition real on-compact transitive group actions. The geometric phases of both cases will be described.

In this work, we use the theory of nonlinear realizations for the construction of non-Abelian geometric phases. We construct the Aharonov-Anandan phase using the CCWZ theory of nonlinear realizations on the Grassmann manifold and identify the total non-Abelian phase (dynamical and geometric) as the  $U(k)$ -valued cocycle of the  $U(N)$  action on the Grassmann manifold. Next, since, in the BKMU theory, the homogeneous spaces allow transitive actions of non-compact lie groups, we construct generalizations corresponding to non

self-adjoint dynamics, where the geometric phase becomes the group cocycle of the corresponding non-compact group. We make another generalization by replacing the Grassmann manifold by a generalized flag manifold to describe the non-Abelian geometric phase of isospectral dynamics of density matrices. We show how the latter result is related the Uhlmann's phase [8].

## 1 Control systems on principal bundles

We consider a quantum system living in a Hilbert space  $\mathcal{H} \cong \mathbb{C}^k$ ; we suppose that the system's Hilbert space  $\mathcal{H}$  is embedded into a fixed larger Hilbert space  $\mathcal{W} \cong \mathbb{C}^N$ . In addition, we suppose that we have in our disposal a set of Hamiltonians generating unitary transformations in the larger Hilbert space, which do not, in general, leave our system's subspace  $\mathcal{H}$  invariant. If we want to use this setting to generate unitary transformations within our initial Hilbert space  $\mathcal{H}$ , we need to carefully design the evolution such that:

1. The Hilbert space  $\mathcal{H}$  returns to its original embedding at the end of an evolution cycle.
2. At the end of the evolution cycle the Hilbert space  $\mathcal{H}$  becomes unitarily rotated by a group element  $h \in U(\mathcal{H}) \cong U(k)$ .

let  $P_{\mathcal{H}} \in \mathcal{L}(\mathcal{W})$  be the orthogonal projector onto  $\mathcal{H}$ . The  $U(N)$  orbit of  $P_{\mathcal{H}}$  in  $\mathcal{L}(\mathcal{W})$  is a Grassmannian  $\text{Gr}(k, N)$ , which is the base space of a principal  $(U(N-k) \times U(k))$  bundle which is in addition isomorphic to the group  $U(N)$ .

$$\begin{array}{c}
 U(N-k) \times U(k) \\
 \downarrow i \\
 U(N) \\
 \downarrow \pi \\
 \text{Gr}(k, N)
 \end{array}$$

A cyclic evolution generated by a one parameter group element  $g(t) \in \text{Map}([0, 1], U(N))$ , such that  $g(0) = e$  and  $g(1) = h \in (U(N-k) \times U(k))$ . This transformation is obtained as the holonomy of the path is the geometric phase of our concern.

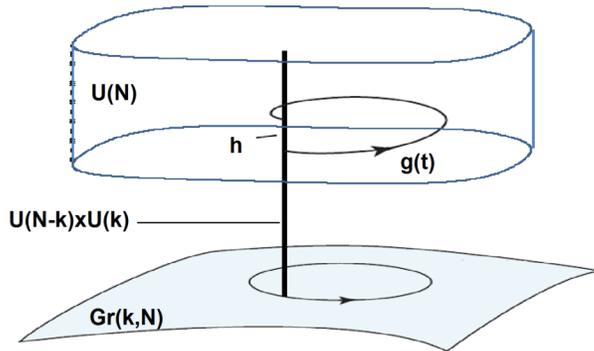


Figure 1: Geometric phase as a path holonomy

The base space of the principal bundle can be viewed as a space of quantum states consisting of the unitary orbit of a density matrix of the form:

$$\rho_0 = \text{diag}\left(\underbrace{\frac{1}{k}, \dots, \frac{1}{k}}_{k\text{-times}}, \underbrace{0, \dots, 0}_{(N-k)\text{-times}}\right) \quad (1)$$

Since, by design, the projected path onto the Grassmannian is closed, the above state is left invariant after the evolution cycle. The holonomy belongs to the isotropy group of  $\rho_0$ , thus it is left invariant. However, we can, because the holonomy lies in its isotropy group. However, this holonomy acts nontrivially on state spaces through bundle maps as follows:

Let

other However, any other state whose density matrix does not commute with  $\rho_0$  would change under the above evolution. We can allow the holonomy to act on a larger class of states by embedding their state space into the Grassmannian. This can be done as follows:

The space of states of a level quantum system living in a Hilbert space  $\mathcal{H} \cong \mathcal{C}^N$  is the set of  $N$  dimensional density matrices:

$$\mathcal{D} = \{\rho \in \mathcal{L}(\mathcal{C}^N) | \rho \geq 0, \text{Tr}(\rho) = 1\} \quad (2)$$

An evolution of the quantum system can be well described by an automorphism of this space. However, this However, there are cases, where different descriptions of the state space or some of its subsets are favorable. For example, suppose that the Hilbert space of the system  $\mathcal{H}$  is a subspace of a fixed larger Hilbert space  $W \cong \mathcal{C}^M$ . Suppose that we can operate only within the larger Hilbert space, for example when the larger Hilbert space is the computational basis of a quantum computing system. Quantum evolution phases appear in systems with parametrized Hamiltonians, where the system is associated with a family of Hamiltonians,

### 1.1 Nonlinear realizations (CCWZ)

Let  $G$  be a compact Lie group,  $H$  a closed subgroup, and  $G/H = gH, g \in G$  be the corresponding left coset space. According to the bundle structure theorem [9],  $G$  is a principal  $H$  bundle over  $G/H$

$$H \xrightarrow{i} G \xrightarrow{\pi} G/H \quad (3)$$

We parametrize the coset space  $G/H$  by a section  $u : G/H \rightarrow G$  according the following commutative diagram:

$$\begin{array}{ccc} G & & \\ \pi \downarrow & u \swarrow & \\ G/H & \xleftarrow{id} & G/H \end{array}$$

Thus, for  $x \in G/H : \pi(u(x)) = x$ .

Choosing  $G/H$  to be a left coset space, the left  $G$  action:  $G \times G/H \rightarrow G/H$  takes the form:

$$g.x = \pi(gu(x)) \quad (4)$$

Thus there must exist a function  $h : G/H \times G \rightarrow H$ , such that:

$$gu(x) = u(g.x)h(x, g) \quad (5)$$

By performing two consecutive group actions, we deduce that  $h(x, g)$  satisfies the cocycle condition:

$$h(x, g_2g_1) = h(g_1.x, g_2)h(x, g_1) \quad (6)$$

The infinitesimal version of equation 5 can be obtained by restricting the action to a one parameter subgroup  $g(t) = e^{sT}$ :

$$\frac{d}{ds}g(t)u(x)|_{s=0} = \frac{d}{ds}(u(g(s).x)h(x, g(s)))|_{s=0} \quad (7)$$

Thus, we have

$$Tu(x) = \nabla_T u(x) + u(x)\Omega_T(x) \quad (8)$$

Where  $\nabla_T \in \text{Vect}(G/H)$  is the vector field on  $G/H$  generating the left group action along  $T$ , and  $\Omega_T(x) \in H$  is the Lie algebra cocycle corresponding to the group cocycle  $h(x, g)$ . The vector fields  $\nabla_T$  satisfies the Lie algebra  $\mathfrak{g}$  commutation relations:

$$[\nabla_{T_1}, \nabla_{T_2}] = \nabla_{[T_1, T_2]} \quad (9)$$

while the Lie algebra cocycles satisfy:

$$\nabla_{T_1}\Omega_{T_2}(x) - \nabla_{T_2}\Omega_{T_1}(x) + [\Omega_{T_1}, \Omega_{T_2}] = \Omega_{[T_1, T_2]} \quad (10)$$

We can already see that the Lie algebra cocycles constitute of two parts:

$$\Omega_T(x) = u(x)^{-1}Tu(x) - u(x)^{-1}\nabla_T u(x) \quad (11)$$

The first part is the generator of the dynamical phase, while the second generates the geometric phase. Since the structure group of the principal bundle is  $H$ , in the overlap between two charts, the parametrizing section  $u(x)$ , transforms according to:

$$u'(x) = u(x)h(x) \quad (12)$$

where  $h(x)$  a smooth  $H$ -valued function in the overlap. The generator of the geometric phase transforms by a gauge transformation:

$$u'(x)^{-1}\nabla_T u'(x) = h(x)^{-1}(u(x)^{-1}\nabla_T u(x))h(x) + h(x)^{-1}\nabla_T h(x) \quad (13)$$

Our purpose is to integrate the Lie algebra cocycles  $\Omega_T(x)$  of equation 8, to obtain the group cocycles  $h(x, g)$ . For this purpose, we choose in 6:  $g_2 = e^{sT}$ , and  $g_1 = g$ , and take the derivative with respect to  $s$  at  $s = 0$ .

We obtain:

$$\frac{d}{ds}h(x, e^{sT}g)|_{s=0} = \frac{d}{ds}h(g.x, e^{sT})h(x, g)|_{s=0} \quad (14)$$

Thus, we get

$$L_T h(x, g) = \Omega_T(g.x)h(x, g) \quad (15)$$

Where,  $L_T \in \text{Vect}(G)$  is the generator of the left  $G$  action on the group manifold.

If we take now an element  $g$  given by an anti-time ordered product:

$$g(t) = \mathcal{AT}e^{\int_0^t T(s)ds} \quad (16)$$

We can integrate equation 15 to obtain:

$$h(x, g(t)) = \mathcal{AT}e^{\int_0^t \Omega_{T(s)}(g((s).x)ds} = \mathcal{AT}e^{\int_0^t \Omega_{T(s)}(\mathcal{AT}e^{\int_0^s T(w)dw}.x)ds} \quad (17)$$

Equation 17 is the main result of this work. It constitutes a combination of the non-Abelian geometric and the dynamical phases. The right hand side will be shown to coincide with the Aharonov-Anandan phase when we choose the coset space  $G/H$  to be a Grassmann manifold. In addition, it will be used in the non-self adjoint generalizations.

*Proof of equation 17:*

The anti-time ordered product is given by the following limit:

$$g(t) = \mathcal{AT}e^{\int_0^t T(s)ds} = \lim_{\substack{\epsilon \rightarrow 0 \\ N \rightarrow \infty \\ \epsilon N = t}} \prod_{j=1}^N g_{N-j+1} \quad (18)$$

Where:

$$g_j = 1 + \epsilon T(j\epsilon)$$

Substituting 18 into the left hand side of 17, and consecutively using the cocycle condition, we obtain:

$$h(x, g(t)) = \lim_{\substack{\epsilon \rightarrow 0 \\ N \rightarrow \infty \\ \epsilon N = t}} \prod_{j=1}^N h(x_{N-j}, g_{N-j+1}) \quad (19)$$

Where,

$$x_n = g_n g_{n-1} \dots g_1 \cdot x$$

Since

$$h(x_{N-j}, g_{N-j+1}) = h(x_{N-j}, 1 + \epsilon T((N-j+1)\epsilon)) = 1 + \epsilon \Omega_{T((N-j+1)\epsilon)}(x_{N-j})$$

We obtain:

$$h(x, g(t)) = \lim_{\substack{\epsilon \rightarrow 0 \\ N \rightarrow \infty \\ \epsilon N = t}} \prod_{j=1}^N (1 + \epsilon \Omega_{T((N-j+1)\epsilon)}(x_{N-j})) \quad (20)$$

The right hand side of equation 17 can also be written as a limit:

$$\mathcal{AT}e^{\int_0^t \Omega_{T(s)}(g((s) \cdot x) ds} = \lim_{\substack{\epsilon \rightarrow 0 \\ N \rightarrow \infty \\ \epsilon N = t}} \prod_{j=1}^N (1 + \epsilon \Omega_{T((N-j)\epsilon)}(x_{N-j})) \quad (21)$$

The right hand sides of equations 20 and 21 coincide in the limit, which completes the proof.

Since  $G$  and  $H$  are compact,  $G/H$  is reductive, i.e., the Lie algebra  $\mathfrak{g} = T_e G$  can be decomposed as:

$$\mathfrak{g} = \mathfrak{h} \oplus \mathfrak{M} \quad (22)$$

where  $\mathfrak{h}$ , is the Lie algebra of  $H$  and

$$Ad(H)\mathfrak{M} \subset \mathfrak{M} \quad (23)$$

According to the slice lemma [10], there is a neighborhood  $U \subset G/H$  of  $0 = \pi(e)$ , in which the section  $u(x)$ , can be chosen as:

$$u(x) = e^X = e^{\sum_{\alpha=0}^{\dim \mathcal{M}} x^\alpha T_\alpha} \quad (24)$$

such that every element in  $\pi^{-1}(U)$  can be uniquely written as:

$$g = e^X h, \quad X \in \mathcal{M}, \quad h \in H \quad (25)$$

The left group action of  $h \in H$  in the neighborhood  $U$  takes the form:

$$he^X = he^X h^{-1} h = e^{\text{ad}(h)X} h$$

Thus the group action and the cocycle have the following forms in the particular case  $h \in H$ :

$$u(h.x) = hu(x)h^{-1} \quad (26)$$

$$h(x, h) = h \quad (27)$$

The second equality extends to the whole of  $G/H$  by continuity.

$$\begin{aligned} \rho(e) &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, & \rho((12)) &= \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \\ \rho((23)) &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, & \rho((13)) &= \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \\ \rho((123)) &= \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, & \rho((132)) &= \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}. \end{aligned}$$

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$$\int_a^b u \frac{d^2 v}{dx^2} dx = u \frac{dv}{dx} \Big|_a^b - \int_a^b \frac{du}{dx} \frac{dv}{dx} dx. \quad (28)$$

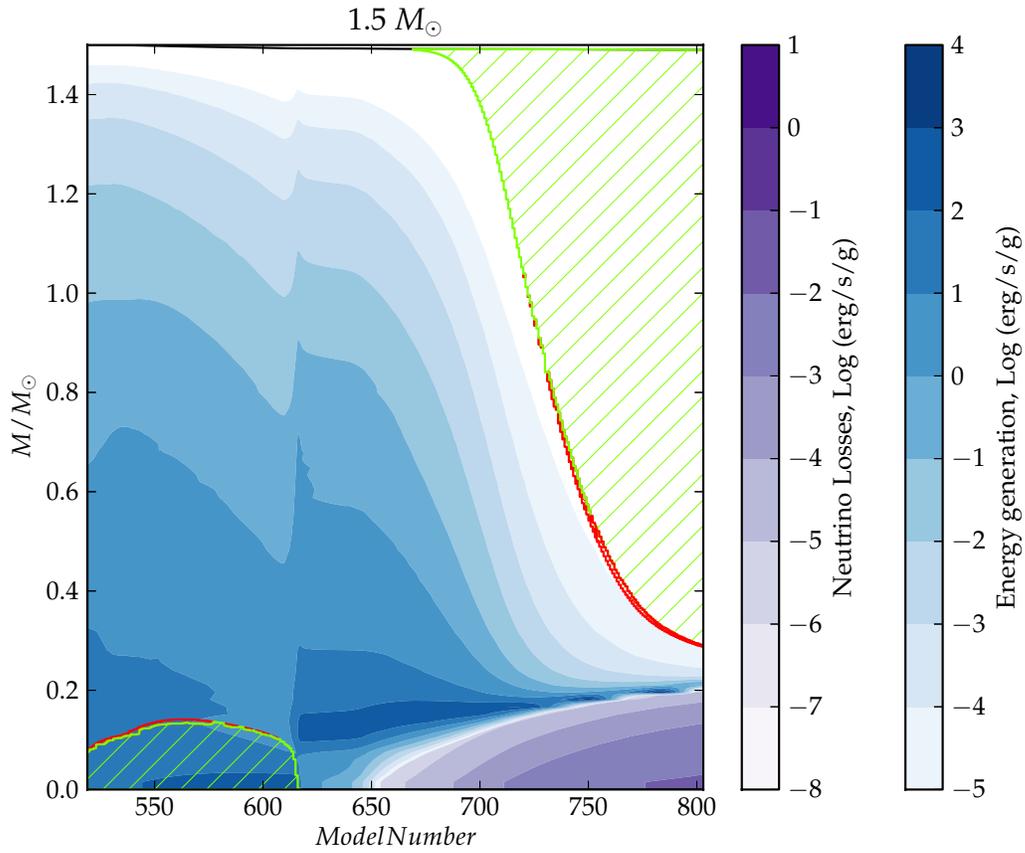


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## Section

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Table 1: Different quantities and qualities of  $T_{\text{shell}}$

Heading	$r_c$ (km)	$T_{\text{shell}}$ (s)	$t_{\text{waves}}$ (s)	$\mathcal{M}$	$\omega_c$ (rad/s)	$P_{\text{min}}$ (s)	$P_{\text{min,Fe}}$ (s)	$P_{\text{min,NS}}$ (s)
Row	$1.6 \times 10^7$	$4 \times 10^{13}$	$2 \times 10^5$	0.06	$3 \times 10^{-6}$	$2 \times 10^5$	40	$2 \times 10^{-3}$
Row	$9.7 \times 10^3$	$3 \times 10^8$	$10^6$	0.002	$4 \times 10^{-3}$	$2 \times 10^3$	50	$2.5 \times 10^{-3}$
Row	$3.6 \times 10^3$	$4 \times 10^6$	$10^5$	0.004	$2 \times 10^{-2}$	-	-	-
Row	$1.7 \times 10^3$	$7 \times 10^3$	$2 \times 10^3$	0.02	$4 \times 10^{-1}$	-	-	-

## 2 Section

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