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2 **Title:** TRAMPOLine: a Temporal Relative Abundance-focused Multi-sPecies Occupancy
3 model, illustrated using a fossil community

4 **Running head:** Relative abundance occupancy model

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16 LHL and THE developed earlier versions of the model. TR brought the model development
17 to completion, wrote the code and performed the analyses. TR and LHL wrote the first draft
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19 **Data accessibility statement:** Should this manuscript be accepted, the data supporting the
20 results will be archived in an appropriate public repository and the data DOI will be included
21 at the end of the article. Code and data for review are available at

22 <https://github.com/trondreitan/TRAMPOLine>

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24 **Abstract**

25 The relative abundance of species is temporally varying, but estimating abundance, given
26 incomplete and biased sampling is challenging. Here, we describe a new occupancy model,
27 TRAMPOLine (Temporal Relative Abundance-focused Multi-sPecies Occupancy model) in a
28 hierarchical Bayesian framework, where occupancy and detection are modeled as a means to
29 estimate relative abundance. TRAMPOLine can be applied to temporal occupancy data with
30 sub-samples. We demonstrate TRAMPOLine using a fossil community of benthic organisms
31 to estimate relative abundance dynamics of several focal species over 2.3 million years, by
32 drawing on information provided by non-focal species observed in the same community. We
33 expanded TRAMPOLine by adding random effects of species and time-intervals (geological
34 formations) and explored potential explanatory factors (paleoenvironmental proxies) and
35 temporal autocorrelation that could provide extra information on unsampled geological time-
36 intervals. TRAMPOLine is applicable across a wide range of questions on species-level
37 dynamics in contemporary and palaeoecological community settings.

38 **Introduction**

39 Occupancy modeling in statistical ecology (King 2014) seeks to tease apart true site-
40 occupancy and observations of species within sites by the explicit modeling of both
41 ecological and detection processes (MacKenzie *et al.* 2017). Occupancy data are commonly
42 collected as presence-absence data replicated within multiple sites. While occupancy
43 probability is often the focus of occupancy modeling, it is also used to monitor the
44 persistence of populations, estimate species richness, understand habitat preferences and to
45 infer abundance (MacKenzie *et al.* 2017), the last of which is the our focus here.

46 Understanding the complex drivers of population dynamics and their interactions
47 require robust empirical estimates of changing abundance (Sutherland *et al.* 2013), Here we
48 develop TRAMPOLine, a Temporal Relative Abundance-focused Multi-species Occupancy
49 model that can be applied to communities where data are organized as sites in which sub-sites
50 are observed for multiple species over multiple time-intervals. We will demonstrate our
51 model with a fossil benthic community (see methods and SI) but our model is applicable to
52 diverse systems and ecological disciplines, including contemporary sessile plant or marine
53 benthic communities (Marine and Plant Ecology), other fossil data including pollen and
54 microfossil communities (Archeology, Micropaleontology, Quaternary Science), as well as
55 eDNA data (metagenomics) in which subsamples from sites are analysed separately, over
56 several time-intervals.

57 In TRAMPOLine, local abundance (i.e. site-level abundance, given occupancy), is
58 derived from detection through a point-process assumption. Here, the detection of a species
59 in a sub-sample within a site is derived from a Poisson process with expected value
60 proportional to local abundance. Through this, our aim is to estimate relative abundance of
61 multiple species while drawing on information from other species within the same
62 community and integrating information from multiple sites across time. In contrast, early

63 occupancy models were applied to single-species and did not include counts within sites
64 (MacKenzie *et al.* 2002, 2003). Later, extra information harbored in data in the form of
65 multiple-encounters within sites, were embraced by occupancy modelers. The first model that
66 estimates abundance from occupancy data, including counts, for a single species, the Royle-
67 Nichols (RN) model, assumed that detection probability increases with local abundance
68 (Royle *et al.* 2005). Yamaura *et al.* (2010) then developed a model that combines the RN
69 model with a multi-species approach (Dorazio *et al.* 2006), in order to infer the number of
70 species in the community using data augmentation and by assuming that abundance affects
71 detection. The model we develop here is different from previous hierarchical multispecies
72 occupancy and abundance models (Iknayan *et al.* 2014; Devarajan *et al.* 2020) as these
73 models are focused on estimating species richness (including those that are undetected), but
74 leverage abundance for species richness estimation. Here we are conversely interested in
75 abundance. We factorize sampling (i.e. detection) into shared (species-independent) and
76 species-dependent components using random factors, such that the uncertainty for a given
77 time-interval is informed by the variation found in others. These random effects handle time-
78 interval specific sampling differences, as well as fluctuations common to all species involved,
79 i.e. components irrelevant to relative abundance.

80 By describing how the relative abundance, and secondarily, the occupancy probability
81 of various species have changed over time, TRAMPOLine allows us to hypothesize the roles
82 of potential drivers of ecological waxing and waning. In this methodological contribution, we
83 briefly describe a empirical system to which TRAMPOLine can be applied as an example, then
84 develop a model to extract relevant (paleo)ecological parameters from this system. Using
85 simulated data, we explore if ecological dynamics can be accurately inferred using our
86 model. Last, we discuss the utility of our model for diverse systems and suggest venues for
87 the expansion of our model.

88 **Materials and methods**

89 ***Study system***

90 To illustrate how TRAMPOline can be applied, we use an empirical system of fossilized
91 benthic organisms spanning 2.3 million years found in the Wanganui Basin, (Carter & Naish
92 1998; Proust *et al.* 2005; Pillans 2017) as detailed in the SI. We sampled 9 time-intervals in a
93 total of 119 sites (see Fig. 1 for a schematic representation), in which the number of sub-
94 samples varied between 30-50 (see Table S1 and SI for details). We tabulated the observed
95 presence of three focal species namely *Antharcthoa tongima*, *Escharoides excavata* and
96 *Arachnopusia unicornis* (Fig. S1) in each subsample for all 9 time-intervals and 119 sites. We
97 also introduce a fourth “species”, the superspecies, which represents all other bryozoan
98 species excluding the three focal species. This superspecies information contributes to our
99 estimates of relative abundance for the three focal species (see model description). Since the
100 formations (time-intervals) were chosen because they are known to harbor bryozoans, the
101 superspecies is assumed to always be present, i.e. occupancy probability=1. In other
102 applications, the occupancy probability of the superspecies can be estimated within the
103 model. Note that there is ample among-formation, within-formation and among-species
104 variation in the ratio of examined shells with observations of encrusting bryozoans, where
105 non-observation includes both the lack of detection and non- occupancy (Fig. S2).

106

107 ***Model description***

108 Our main objective is to estimate the temporal (i.e. formation-to-formation) dynamics of
109 relative abundances for each focal species using presence/absence observations on sub-
110 samples (shells) from different sites (Fig.1, Fig. S1). There are two probabilities at play; the
111 probability that a species occupied a given site i.e. the occupancy probability, Ψ , and the
112 probability that a sub-sample has at least one observation of the focal species, given

113 occupancy, i.e., the detection probability, p . The probability that a species is found on a given
114 sub-sample is thus Ψp , where Ψ operates on the site-level while p operates on the sub-
115 sample-level. The occupancy and detection probabilities will be functions of various
116 parameters and random factors, and can be specific to the site i belonging to a specific time-
117 interval, and the species, s . Thus, we will write $\Psi_{i,s}(\theta)$ and $p_{i,s}(\theta)$ for the occupancy and
118 detection probabilities respectively, where θ is the set of top parameters and random
119 variables of the model in question (Fig. 2). The relative abundances for the focal species and
120 time-intervals will be derived from these two sets of probabilities as such: the site-dependent
121 detection probability is decomposed into a time-interval-dependent component and a local
122 fluctuation. Working on the time-interval-dependent scale, a Poisson process with intensity
123 proportional to the local abundance, given occupancy, determines the detection probability.
124 The abundance of a species in a given time-interval is then the expected local abundance
125 (unconditioned on occupancy), or in other words, local abundance given occupancy times the
126 occupancy probability. This is determined up to an unknown proportionality constant, but
127 where the latter drops out when calculating relative abundance.

128 We build our models in a step-wise fashion, starting with a standard occupancy model
129 because it is the most familiar, then gradually adding complexity until we have a model with
130 enough elements to allow for relative abundance estimates. The reason for this step-wise
131 presentation is three-fold. The first is to put focus on each of the model components. Second,
132 because MCMC convergence was possible to achieve only when we used the parameter
133 estimates from a simpler model as the starting points for the next, more complex model.
134 Thirdly, because we wanted to justify the model complexities we added, using the Bayes
135 factor as measure of evidence (Jeffreys 1998).

136

137 1. The basic occupancy model

138 The simplest occupancy model (MacKenzie *et al.* 2002) contains only occupancy and
 139 detection probabilities such that number of sub-samples at site i with observations of species
 140 s is a zero-inflated binomial random variable.

141

$$142 \quad y_{i,s} \sim zbin \left(N_i, p_{i,s}(\theta) = \text{logit}^{-1}(\beta_s), \Psi_{i,s}(\theta) = I(s = S) + I(s < S)\text{logit}^{-1}(\alpha_s) \right) \quad (1)$$

143

144 Here, N_i is the total number of sub-samples examined at site i . $I()$ stands for the indicator
 145 function, which takes value 1 when the statement inside is true and 0 if it is false. The
 146 unconditional probability of detection is $p_{i,s}(\theta)\Psi_{i,s}(\theta)$. We express both occupancy and
 147 detection probabilities using a logit-transform, i. e. $\text{logit}(r) \equiv \log\left(\frac{r}{1-r}\right)$, where r is a
 148 probability, for the convenience of expanding the model in the next sections. The two
 149 parameters, α_s and β_s , (see Fig. 2) give regional (i.e. within the Wanganui Basin in our
 150 application) occupancy and detection probabilities for each species respectively, regardless of
 151 time-interval (formation). The parameter set is $\theta = \{\alpha_1, \dots, \alpha_{S-1}, \beta_1, \dots, \beta_S\}$, where S is the
 152 number of species (focus species plus superspecies). Even though we are currently describing
 153 a time-intervals-independent model, we write $\Psi_{i,s}(\theta)$ and $p_{i,s}(\theta)$, since occupancy and
 154 sampling will be derived from parameters that are both species-dependent and site-dependent
 155 (or in practice, time-interval dependent) later. Note however, that $\alpha_{s=S}$ does not appear in the
 156 model, as we assume that the superspecies is always present (leaving us with $2 \times S - 1$
 157 parameters).

158

159 2. Including site-dependent random factors through overdispersion

160 Fluctuations in the local abundance of a species can be modelled by a per site, per species
 161 random factor. Here, site-dependent detection probability is allowed to vary around the
 162 median regional detection probability. If this random factor was normal on the logit-scale,

163 one could either estimate the random factors in a hierarchical Bayesian model or integrate
 164 over the logit-normal distribution, yielding an over-dispersed version of the binomial
 165 distribution (e.g. Harrison 2014). The latter option gives the logit-normal binomial
 166 distribution and simplifies the model, as it removes explicit site-dependency. This
 167 distribution does not, however, have a closed analytical expression (e.g. Schmettow 2009). If
 168 the random effects are instead beta-distributed, we can use the zero-inflated beta-binomial
 169 distribution, which does have an analytical expression.

170

$$171 \quad y_{i,s} \sim z\beta bin \left(N_i, p_{i,s}(\theta) = \text{logit}^{-1}(\beta_s), \kappa_s, \Psi_{i,s}(\theta) = I(s = S) + I(s < S)\text{logit}^{-1}(\alpha_s) \right) \quad (2)$$

172
 173 Here, κ_s describes the species-dependent overdispersion. The parameters set is now $\theta =$
 174 $\{\alpha_1, \dots, \alpha_{S-1}, \beta_1, \dots, \beta_S, \kappa_1, \dots, \kappa_S\}$. The detection and occupancy probabilities depend on the
 175 identity of the time-interval that site belongs to, rather than the site itself, as the
 176 overdispersion account for the variation among sites (at this point no time-interval
 177 dependency has been added). This also holds for later models presented here. The probability
 178 of y observations out of n sub-samples from the zero-inflated beta-binomial distribution with
 179 detection probability, p , overdispersion parameter, κ , and zero-inflation, Ψ , is defined as:

180

$$181 \quad P_{z\beta bin}(y|n, p, \kappa, \Psi) =$$

$$182 \quad (1-\Psi)I(y = 0) + \Psi \frac{\Gamma(n+1)\Gamma(y+\frac{p}{\kappa})\Gamma(n-y+\frac{1-p}{\kappa})\Gamma(\frac{1}{\kappa})}{\Gamma(y+1)\Gamma(n-y+1)\Gamma(n+\frac{1}{\kappa})\Gamma(\frac{p}{\kappa})\Gamma(\frac{1-p}{\kappa})} \quad (3)$$

183

184 The first term of the right hand-side of Eqn (3) up to (but not including) the fractional
 185 expression, describes the zero-inflation, while the second, fractional part describes the beta-
 186 binomial distribution.

187 3. Including species- and formation-dependent random factors

188 We now introduce temporal dynamics by using time-interval-dependent random factors (e.g.
 189 Pacifici *et al.* 2016) that are species-independent, i.e. they summarize dynamics common to
 190 all species in the community. For the detection probability, the random effects imply
 191 fluctuations in the sampling as well as in average density of the community of species in
 192 question. For occupancy, the random effects allow fluctuations in the overall presence of
 193 species in question. The time-intervals with richer data can thus inform estimates for those
 194 with sparser data. The model is now:

195

$$196 \quad y_{i,s} \sim z\beta bin \left(N_i, p_{i,s}(\theta) = \text{logit}^{-1}(\beta_s + u_{f(i)}), \kappa_s, \Psi_{i,s}(\theta) = I(s = S) + I(s < \right.$$

$$197 \quad \left. S)\text{logit}^{-1}(\alpha_s + v_{f(i)}) \right) \quad (4a)$$

$$198 \quad u_f \sim N(0, \sigma_u^2), v_f \sim N(0, \sigma_v^2), \quad (4b)$$

199

200 where $f(i)$ is the time-interval that site i belongs to, u_f and v_f are the new time-interval-
 201 dependent random effects and σ_v and σ_u are the standard deviations of these effects, for
 202 detection and occupancy, respectively. Now, $\theta =$
 203 $\{\alpha_1, \dots, \alpha_{S-1}, \beta_1, \dots, \beta_S, \kappa_1, \dots, \kappa_S, \sigma_u, \sigma_v, u_1, \dots, u_F, v_1, \dots, v_F\}$, where F is the number of
 204 time-intervals (geological formations in our empirical example).

205 While this model (Eqn 4) does allow for dynamics due to time variations in the whole
 206 set of species in the region, the probabilities vary in sync for the different species. In order to
 207 facilitate dynamics that permit fluctuations in the relative species-dependent abundances, we
 208 need random effects that depend on species and formation combinations. When doing so, we
 209 have:

210

211 $y_{i,s} \sim z\beta bin \left(N_i, p_{i,s}(\theta) = \text{logit}^{-1}(\beta_s + u_{f(i)} + \varepsilon_{f(i),s}), \kappa_s, \Psi_{i,s}(\theta) = I(s = S) + \right.$
 212 $\left. I(s < S)\text{logit}^{-1}(\alpha_s + v_{f(i)} + \delta_{f(i),s}) \right)$ (5a)

213 $u_f \sim N(0, \sigma_u^2), v_f \sim N(0, s\sigma_v^2), \delta_{f,s} \sim N(0, \sigma_{\delta,s}^2), \varepsilon_{f,s} \sim N(0, \sigma_{\varepsilon,s}^2)$ (5b)

214

215 where $\varepsilon_{f,s}$ and $\delta_{f,s}$ are the new time-interval- and species-dependent random effects and $\sigma_{\varepsilon,s}$
 216 and $\sigma_{\delta,s}$ are the standard deviations of these effects, for detection and occupancy,
 217 respectively. Our inferred abundances are averages over time as well as space, so it can is
 218 better described as being proportional to an temporally-averaged density and is hence
 219 continuous rather than integer-valued.

220 The time-interval dependent random effects (u_f and v_f) introduced in Eqn. (4) do not
 221 affect the estimation of relative overall abundances (since these are estimated for each
 222 formation), but will take away pure formation dependencies from the species- plus time-
 223 interval dependent random variables, thus removing possible source of bias and make our
 224 uncertainty estimates more precise.

225 The parameter set is now $\theta = \{\alpha_1, \dots, \alpha_{S-1}, \beta_1, \dots, \beta_S, \kappa_1, \dots, \kappa_S, \sigma_u, \sigma_v,$
 226 $\sigma_{\delta,1}, \dots, \sigma_{\delta,S-1}, \sigma_{\varepsilon,1}, \dots, \sigma_{\varepsilon,S}, u_1, \dots, u_F, v_1, \dots, v_F, \delta_{1,1}, \dots, \delta_{F,S}, \varepsilon_{f,s}, \dots, \varepsilon_{F,S}\}$. Specifically, our
 227 top parameters (as opposed to the random factors) are
 228 $\{\alpha_1, \dots, \alpha_{S-1}, \beta_1, \dots, \beta_S, \kappa_1, \dots, \kappa_S, \sigma_u, \sigma_v, \sigma_{\delta,1}, \dots, \sigma_{\delta,S-1}, \sigma_{\varepsilon,1}, \dots, \sigma_{\varepsilon,S}\}$. We log-transformed all
 229 positive-valued parameters including the standard deviations and over-dispersion parameters,
 230 so that the re-parametrized parameter set allows values along the entire real line. With 3
 231 species and one super-species ($S=4$), our application has 20 ($5 \times S$) top-parameters. In
 232 addition, the inference also needs to handle 81 ($(2S+1) \times F$) random variables (Eqn 5b). We
 233 call Eqn (5) the “full model” i.e. TRAMPOLine, since it has all the necessary component for
 234 estimating the dynamics of relative abundance (shown in Fig. 2).

235 4. A step-wise approach for improving estimation

236 Because the full model is fairly complex and required hierarchically arranged random effects,
237 we utilized Markov chain Monte Carlo (MCMC) sampling for inference (SI section “MCMC
238 for statistical inference”). We used common estimated parameter values from a simpler
239 model when starting a more complex model, in a step-wise fashion (i.e. from Eqn 1 to 2
240 to ...5) as preliminary analyses often failed when starting from a random place in the
241 parameter space. In doing so, we also tested if each increasingly complex model explained
242 the data better, using Bayes factors.

243

244 5. Incorporating explanatory variables

245 We expanded our full model (Eqn 5) by including temporal explanatory variables – in our
246 empirical example pertaining to paleoclimate, as well as auto-correlated processes by using
247 an Ornstein–Uhlenbeck process (SI sections “Model expansions that include explanatory
248 variables” and “Introducing correlations in the random effects”) although results from these
249 are not detailed in the main text. Our motivation for examining and testing these expansions
250 was to develop extended models that predict relative abundances in unmeasured time-
251 intervals with more precision than just using the time-interval-independent median values
252 derived from α_s and β_s . We impose a quadratic term for our explanatory variables (on
253 detection probability, occupancy probability or both) as each species should thrive at an
254 (different) optimal climate, with a given tolerance width. For demonstration, we use two
255 related but different paleoclimate proxies, namely the global $\delta^{18}\text{O}$ data (data from Lisiecki &
256 Raymo 2005) and the North Atlantic magnesium/calcium (Mg/Ca) ratios (data from Sosdian
257 & Rosenthal 2009), both based on measurements from benthic foraminifera, as explanatory
258 variables. These contain complex signals of sea temperature, ice-volume and sea-level
259 changes, all of which potentially affect both the population growth rates (through optimal

260 temperatures and the availability of substrate species) and detection probabilities (through
261 sea-level changes) of our focal species. Whether other applications of TRAMPOLine will
262 benefit from such model extensions is naturally context-dependent..

263

264 6. Estimating relative abundances

265 In this section we estimate the relative abundance estimates of a given species in a given
266 formation. The relative abundance of a species is proportional to the sum of its local
267 abundances given occupancy, $\lambda_{i,s}$, times its occupancy probability $\Psi_{i,s}$. For the ease of
268 reading, we suppress denoting that the elements described are all functions of the model
269 parameter set in this section. Since our model does not contain any site-dependent
270 components (except that absorbed by overdispersion), relative abundance estimate $A_{f,s}$ can be
271 expressed using formation (time-interval) indexes (f) instead of site indexes (i) as such:

272

$$273 A_{f,s} \propto \Psi_{f,s} \lambda_{f,s}. \quad (6)$$

274

275 However, the detection probability, $p_{f,s}$, and the local abundance, $\lambda_{f,s}$, do not scale
276 proportionally to each other. This is because while detection probability has an upper limit,
277 local abundance (i.e. counts of individuals of a given species in a defined area at a given
278 time) does not. To obtain relative abundances, a link between the inferred detection
279 probability of a species in a given formation, $p_{f,s}$, and the time-averaged abundance, $\lambda_{f,s}$,
280 must be formulated. Here we assume that the number of individuals of a species in each sub-
281 sample can be described by a Poisson process, where the Poisson parameter is proportional to
282 the time-averaged abundance. Thus

283

284 $P(\text{at least one individual of species } s \text{ is found in the sub -}$
285 $\text{sample in an occupied site in time - interval } f) = p_{f,s} = 1 - e^{-k\lambda_{f,s}}$
286 (7)

287
288 where k is the proportionality constant. In our application, k will be affected by the
289 preservation probability of bryozoans in the formation, which will in turn affect the time-
290 interval-dependent random effects in Eqns (4-5). In other systems, “preservation” is simply a
291 common observational filter that may or may not be necessary. If such a filter is unnecessary,
292 the time-interval dependent and random effects may be excluded. The time-interval-
293 dependent random effects and k , are also affected by species-independent fluctuations in the
294 regional overall abundance. We assume that k is species-independent (i.e. we assume that
295 individuals, regardless of their species identity, in a given time-interval have equal chances of
296 getting preserved). Eqn (7) ensures that while the temporally-averaged abundance of species
297 s can be any positive real number larger than zero, the detection probability will be between
298 zero and one. Up to the proportionality constant, k , Eqn (7) is Eqn (1) in (Yamaura *et al.*
299 2010). In most, if not all previous occupancy models that incorporate counts, spatial area is
300 strictly defined and the time window of sampling so short that one can assume the counts of
301 individuals (integers) inhabiting that area do not vary over the given study. In contrast, the
302 abundances we are interested in are averaged over both time and space such that they must be
303 represented by positive real numbers rather than integers. We now calculate the relative
304 abundance, $R_{f,s}$ using Eqs. (6) and (7):

305
306
$$R_{f,s} = \frac{A_{f,s}}{\sum_{s'=1}^S A_{f,s'}} = \frac{\Psi_{f,s}\lambda_{f,s}}{\sum_{s'=1}^S \Psi_{f,s'}\lambda_{f,s'}} = \frac{k\Psi_{f,s}\lambda_{f,s}}{\sum_{s'=1}^S k\Psi_{f,s'}\lambda_{f,s'}} = \frac{\Psi_{f,s}\log(1-p_{f,s})}{\sum_{s'=1}^S \Psi_{f,s'}\log(1-p_{f,s'})} \quad (8)$$

307

308 Note that the proportionality constant in Eqn. 7 cancels out. Thus, the relative abundance of a
309 focal species can be estimated from the components of the occupancy model.

310 For an alternative modelling approach to estimate relative abundance, built-up from
311 the local abundance-related parameters, $\lambda_{f,s}$, rather than detection probabilities, see SI
312 “Description of the local abundance focused model”.

313

314 7. Simulations

315 We performed two sets of simulations. The first “parameter-focused simulation study” was
316 performed to check how well estimated parameters and derived quantities (occupancy
317 probabilities, detection probabilities and relative abundances) can be inferred from data. The
318 second “occupancy dynamics-focused simulation study” was performed to check under what
319 sampling regimes we could detect occupancy probability dynamics when the parameters were
320 as estimated in the empirical data.

321

322 For the parameter-focused simulation study, we generated 100 datasets from a
323 common parameter set that reflects idealized but plausible scenarios for the four species, and
324 analyzed each dataset separately. All simulations used 10 sites per formation, closer to the
325 lower end of our empirical data (Table S1) and 60 shells per site, closer to the maximum of
326 our empirical data, the upper limit of what is reasonable in the field. We varied the species-
327 dependent constants for occupancy and detection among the species. For instance, species 3
328 (SI Figs. S16, S17) is assigned an elevated detection but lower occupancy probabilities
329 compared to estimates from our actual dataset. This would decrease estimation uncertainty
330 compared to our actual data, thus making bias easier to detect and occupancy easier to
331 untangle from detection. Species 1 was assigned occupancy dynamics (SI Fig. S16) and
332 species 2 was assigned detection dynamics (SI Fig. S17). While it might have been ideal to

333 simulate all combinations of parameters, it is not computationally realistic. We urge future
334 users of TRAMPOLine to run simulations to verify estimates specific to their needs, such as
335 we have done here. See SI section “Parameter-focused simulation study” for further details.

336

337 For the occupancy dynamics-focused simulation study, we generated data under different
338 sampling intensities (10, 20, 30, 50, 100 and 1000 sites per formation and 60, 100, 200, 400
339 and 1000 shells per site) and analyzed these data using the model and parameter estimates
340 developed for our empirical data. Here, we were specifically interested in checking
341 whether occupancy dynamics are detectable under different sampling scenarios (see SI
342 “Occupancy dynamics-focused simulation study”).

343

344 **Results**

345 *Empirical findings*

346 We found that including both the time-interval-dependent (i.e. formation-dependent) random
347 effects (introduced in Eqn 4) and the time-interval- and species-dependent random effects
348 (introduced in Eqn 5) improved the description of our empirical data (SI Table S2). In other
349 words, the full model described in Eqn (5) (Fig. 2) was preferred based on Bayes Factors,
350 implying that the occupancy and detectability of the different bryozoan species varied with
351 time-intervals (formation). However, including paleoclimate explanatory variables or auto-
352 correlated random effects did not improve our model (SI Table S2). In other words, we
353 currently do not have any component in our models that allow us to predict relative
354 abundance for unmeasured time-intervals using information beyond the median detection and
355 occupancy probabilities given by α_s and β_s for our empirical data. The Bayes factor did not
356 resolve the choice between the “local abundance focused model” and the full model, and it
357 gave highly similar estimates of relative abundances (see SI).

358 The overdispersion parameters, κ_s , were estimated to 0.09, 0.05, 0.04 and 0.07 for
359 *Antharcthoa tongima*, *Escharoides excavata* and *Arachnopusia unicornis* and the
360 superspecies, respectively (see Table S3 for credibility bands), where $\kappa_s = 0$ means no
361 overdispersion. While these estimates are very close to zero, they represent overdispersion
362 that effectively double the variance, compared to no overdispersion (see SI Fig. S6).

363 The uncertainty surrounding the occupancy probability of each of the focal species is
364 quite large (Fig. 3), where we cannot establish that occupancy is well below 1.0 for any
365 combination of species and formation. Detection probabilities estimated from our full model
366 are also shown in Fig. 4. Note that the relative changes in detection probabilities are similar
367 to the dynamics of the raw data (Fig. S2).

368 By combining occupancy and detection probabilities, we can estimate the relative
369 abundance using Eqn (8) (Fig. 5 and SI Figs. S5 and S11). The relative abundances of the
370 superspecies and *A. tongima* are estimated with relatively high precision and vary
371 significantly over time. The relative abundances of *E. excavata* and *A. unicornis* are
372 estimated with much greater uncertainty.

373 *Simulation results*

374 The parameter-focused simulation study shows a spread of the estimates around the
375 true values for both parameters (SI Figs. S12-15) and the derived quantities of occupancy
376 probabilities (SI Fig. S16), detection probabilities (SI Fig. S17) and relative abundances (Fig.
377 6). Although these estimates are spread quite evenly around both sides of the actual values,
378 minute biases, expected given our informative priors and non-linear transformations, were
379 found, but not cause for worry (see the SI section on the parameter-focuses simulation study).

380 The results of occupancy dynamics-focused simulation study that is specific to our
381 empirical study indicate that even large volumes of data cannot distinguish occupancy

382 dynamics (Table S4) within or among the focal species with the possible exception of
383 *Escharoides excavata* (see SI for details).

384

385 **Discussion**

386 Ecologists are interested in estimating changing relative abundance because it is a
387 prime window into population dynamics (Sutherland *et al.* 2013). On a shorter time scale,
388 understanding how environmental attributes and species traits affect population changes
389 within communities are not only key to ecological understanding but also conservation
390 management (Bowler *et al.* 2018). On a longer time scale, the changing the relative
391 abundance of fossil taxa have, in addition, the potential for supplying direct information on
392 the evolution of phenotypes and changing ecological interactions (e.g. Liow *et al.* 2019) to
393 enable linking paleoecological dynamics to evolutionary changes. However, estimating
394 abundance or density in nature is challenging, regardless of the characteristics of organism
395 (e.g. sessile or motile, small-bodied or large-bodied), the type of data (e.g. direct counts,
396 capture-recapture data), or the time-scale involved (e.g. seasonal, yearly or paleoecological
397 data). Occupancy modeling, which explicitly models sampling probabilities when estimating
398 parameters of biological interest, including changes in relative abundance, is one powerful
399 way of incorporating different sources of data heterogeneity and uncertainty. While
400 occupancy modeling is increasingly widespread in “traditional” ecological studies (Bailey *et*
401 *al.* 2013), is yet to be applied regularly in eDNA or metagenomics surveys (Da Silva Neto *et*
402 *al.* 2020; McClenaghan *et al.* 2020) and also lags behind in paleoecology (Liow 2013). We
403 believe TRAMPOLine has broad applicability in many systems where sub-samples within
404 sites are surveyed with relative ease and where relative abundance rather than species
405 richness is of interest.

406 To briefly elaborate on the applicability of TRAMPOline in paleoecological settings,
407 we emphasize that fossil sampling probability is far from one, not least because preservation
408 is far from guaranteed (Kidwell & Holland 2002). Traditionally in paleoecology, however,
409 there is an underlying assumption, usually implicit, that preservation (and hence the sampling
410 of preserved organisms) is comparable across samples and sites, sometimes even across time-
411 intervals, as long as sampling is standardized. Here, what we termed “detection ratios” are
412 usually presented as estimates of relative abundance (Kidwell 2002; Currano *et al.* 2008;
413 Espinosa *et al.* 2020) . However, we know from simulations and ecological studies that this
414 assumption is problematic (Iknayan *et al.* 2014; MacKenzie *et al.* 2017). Not only is it
415 important to progress beyond tabulations of paleoecological data for improved inferences,
416 parameters estimated using fossil data should be as comparable as possible with the those
417 estimated using living organisms. This will allow us to infer historical baselines for
418 conservation applications and to gain a better understanding of changing biota over longer
419 timescales for which we may have analogue crisis situations (Harnik *et al.* 2012).

420 Instead of using the observed presence or absence of species, we could have instead
421 used the counts of the number of individuals of a given species in each sub-sample. If we
422 used the latter, we would have built a model similar to an N-mixture model (Royle 2004).
423 However, the sub-samples in our example (shells or fragments thereof) varied in volume and
424 these differences are expected to affect the number of individuals (colonies in our case). But
425 shell size (i.e. sub-sample size) was not quantified, hence a random factor for sub-samples
426 would be needed to account for this variation. This inclusion, however, would massively
427 increase model complexity while introducing an uncertainty that would make the extra
428 information (counts per shell in our case) of little relevance. Since the computational cost
429 would dramatically increase while the outcome was intuitively not expected to improve

430 significantly, we decided against this route for our empirical demonstration. However, in
431 other applications, sub-sample size can be standardized or controlled for.

432 We note several extensions to our models that can be considered, with regards to our
433 empirical system. First, there are other sources of variation that we did not take into account,
434 including the species of the shell substrate (e.g. some were cockles and others were scallops)
435 and their size as mentioned above, both of which may be selected by the bryozoan species
436 involved and/or preferentially preserved. The information can be potentially collected in
437 future studies that could improve the estimates. Second, we could potentially handle the
438 number of colonies observed for each focal species per shell, since this could give an extra
439 indication of the local abundance of each species. However, in addition to more time-
440 consuming data collection, one would also have to introduce a random variable per shell, as
441 mentioned above. Third, there are huge spans of time in which we are not able to sample
442 bryozoans because suitable material was not deposited. We used two paleoenvironmental
443 proxies ($\delta^{18}\text{O}$ and Mg/Ca ratios) as covariates in expanded models (SI) in hope that they
444 contained predictive information we could use on unsampled time-intervals. While neither of
445 the two we had published data for were informative, it is possible that other
446 paleoenvironmental proxies, published or yet to be collected, could be used for this purpose.

447 One lesson learnt from our empirical modelling is that while we are able to estimate
448 the dynamics of relative abundance (Fig. 5), the dynamics of occupancy are challenging to
449 grasp in our system. Our occupancy dynamics-focused simulations show that reliably getting
450 occupancy estimates that vary from formation to formation requires unfeasibly intense
451 sampling protocols for our choice of species, with the possible exception of *Escharoides*
452 *excavata* though the requirements there were also quite demanding (see SI). The estimated
453 occupancy probabilities are high while the detection probabilities are relatively low (Figs. 3
454 and 4), a reason why occupancy probabilities and hence dynamics were elusive. In retrospect,

455 if we had chosen species that were more selective of the sites they choose settle in, the
456 occupancy dynamics may have been easier to estimate. Detecting occupancy dynamics was
457 not the principal goal of the study, but in studies where this is of principal concern, such
458 issues should be considered before extensive data collection.

459

460 With our work, we hope that more paleoecologists will consider occupancy modeling
461 as a means to estimate relevant ecological parameters; ecological modelers will pick up
462 where we left off to improve the inference of biologically relevant parameters using a
463 challenging but rich fossil record; and that biologists with very different types of data but
464 similar data structure and questions, such as those analyzing site-specific eDNA to
465 understand relative abundance, will find use for TRAMPOLine.

466

467 **Code**

468 The code and data for all analyses are provided at
469 <https://github.com/trondreitan/TRAMPOLine>

470

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477

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552 detection/nondetection data. *J. Appl. Ecol.*, 48, 67–75.

553

554 **Figure captions**

555 **Figure 1:** Each thick bordered open rectangle represents a time-interval (two are illustrated
556 more fully, the first time-interval, T1, and the n^{th} time-interval, Tn). Within each time-
557 interval, Sites (dotted rectangles) are sampled (two are more fully illustrated in each). Within
558 each site, there are subsamples (smaller, solid bordered rectangles) in which different species
559 (solid shapes) are observed. The open circle represents the super species, which in our case,
560 we assume to be present in all sites, even if not sampled in all subsamples.

561

562 **Figure 2.** This figure summarizes our full hierarchical occupancy model, TRAMPOLine,
563 composed of top parameters and random factors that describe their overdispersion (Eqn 5).
564 Data are denoted as triangles where N are the number of sites and y the shells from site i
565 where species s is observed. Black circles denote occupancy parameters, white circles denote
566 detection parameters and grey circle denotes the overdispersion parameter. An arrow from an
567 element A (i.e. circle, triangle or rectangle) to another B, denotes that B is conditioned on A
568 either by a function or a distribution (see text for details).

569

570 **Figure 3.** Estimates are from our full model where black lines join the species posterior
571 median occupancy for each formation (time-interval) plotted in the middle of the age range of
572 the given formation. Grey lines show 95% posterior credibility intervals for the estimates.
573 Note that the superspecies is not plotted here as its occupancy is assumed to be 1 throughout.

574

575 **Figure 4: Estimated detection probabilities.** Estimates are from our full model where black
576 lines join the species median detection probabilities (plotted on log scale) for each formation
577 (time-interval). Grey lines show 95% posterior credibility intervals for the estimates.

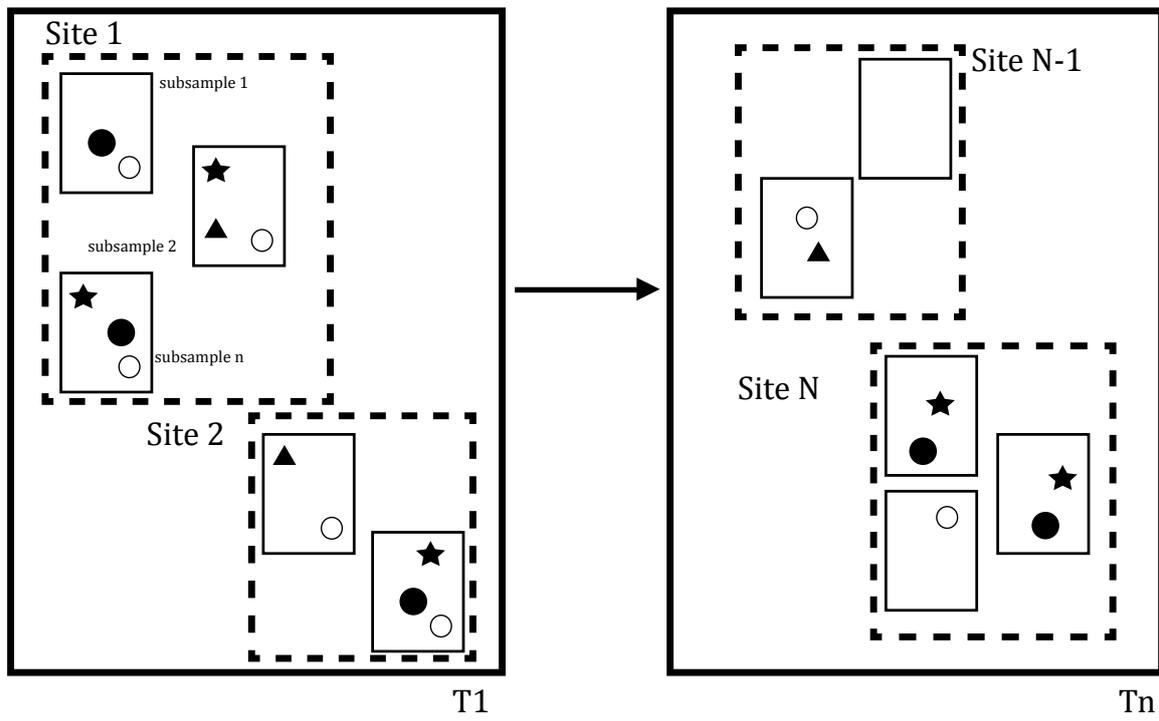
578

579 **Figure 5: Estimated relative abundance.** Estimates are from our full model where black
580 lines join the species mean relative abundance (plotted on a log scale, except for the
581 Superspecies for visibility) for each formation (time-interval). Grey lines show 95% posterior
582 credibility intervals for the estimates.

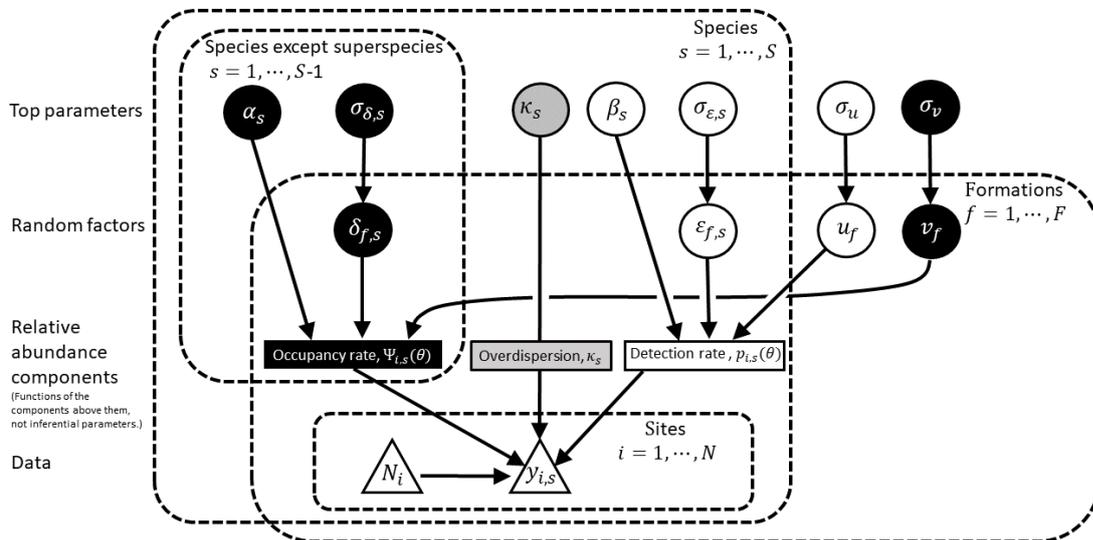
583

584 **Figure 6: Relative abundances from the parameter-focused simulation study.** Solid lines
585 show the true relative abundances for the various species and formations, while the points are
586 estimates from the 100 simulated datasets.

587 **Figure 1: A schematic diagram to show the sampling scheme for TRAMPOLine**



591 **Figure 2: TRAMPOLINE: Full hierarchical occupancy model to estimate relative**
 592 **abundance**

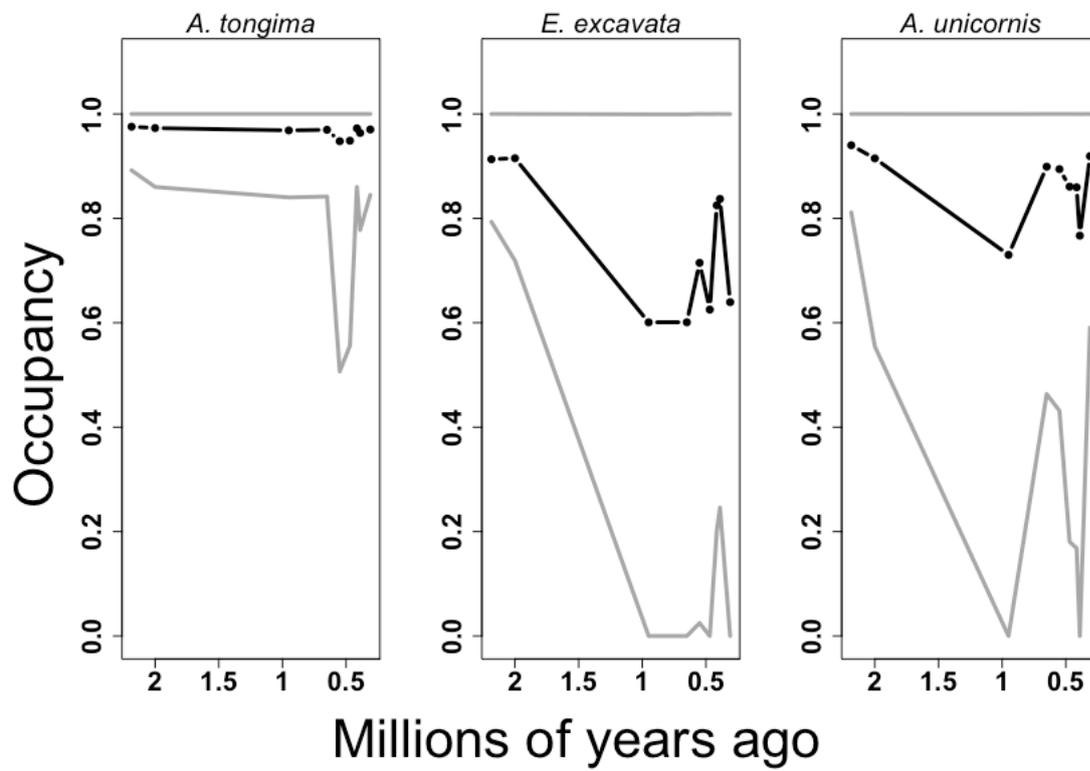


593

594

595

596 **Figure 3: Estimated occupancy probabilities for the three focal species.**

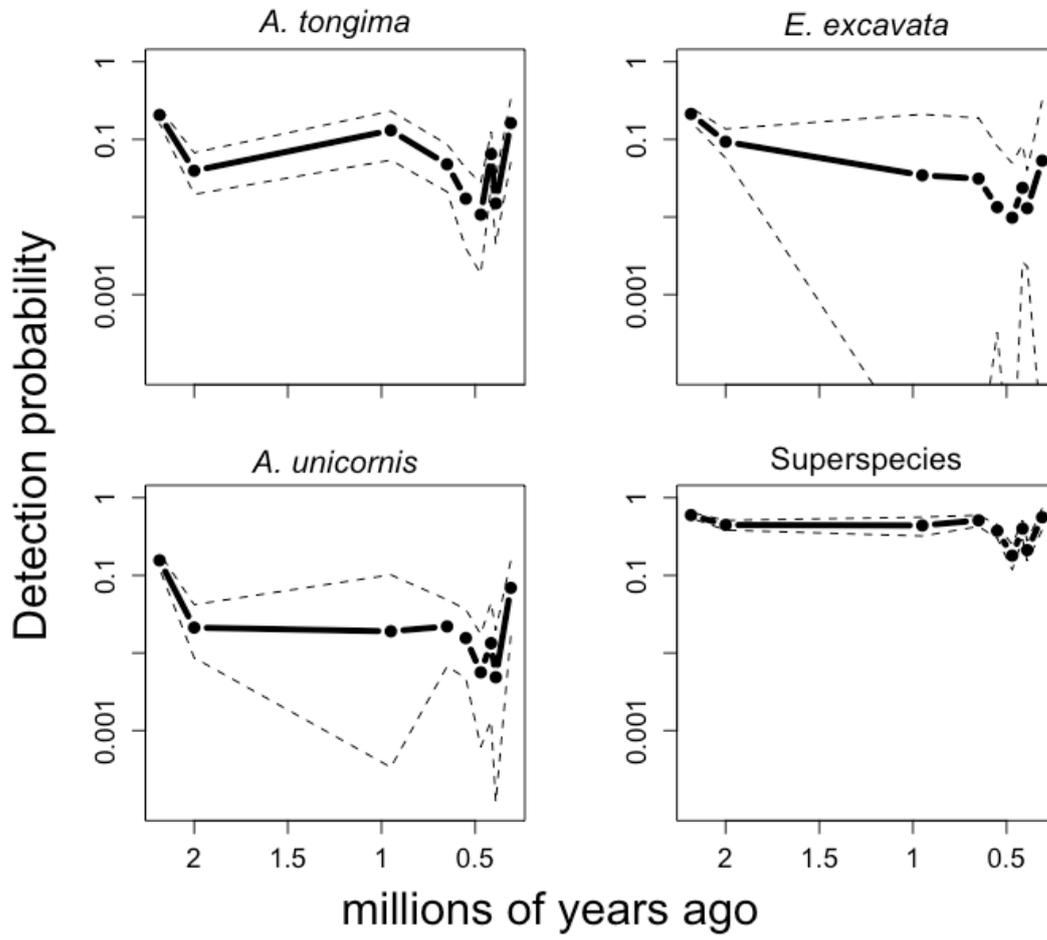


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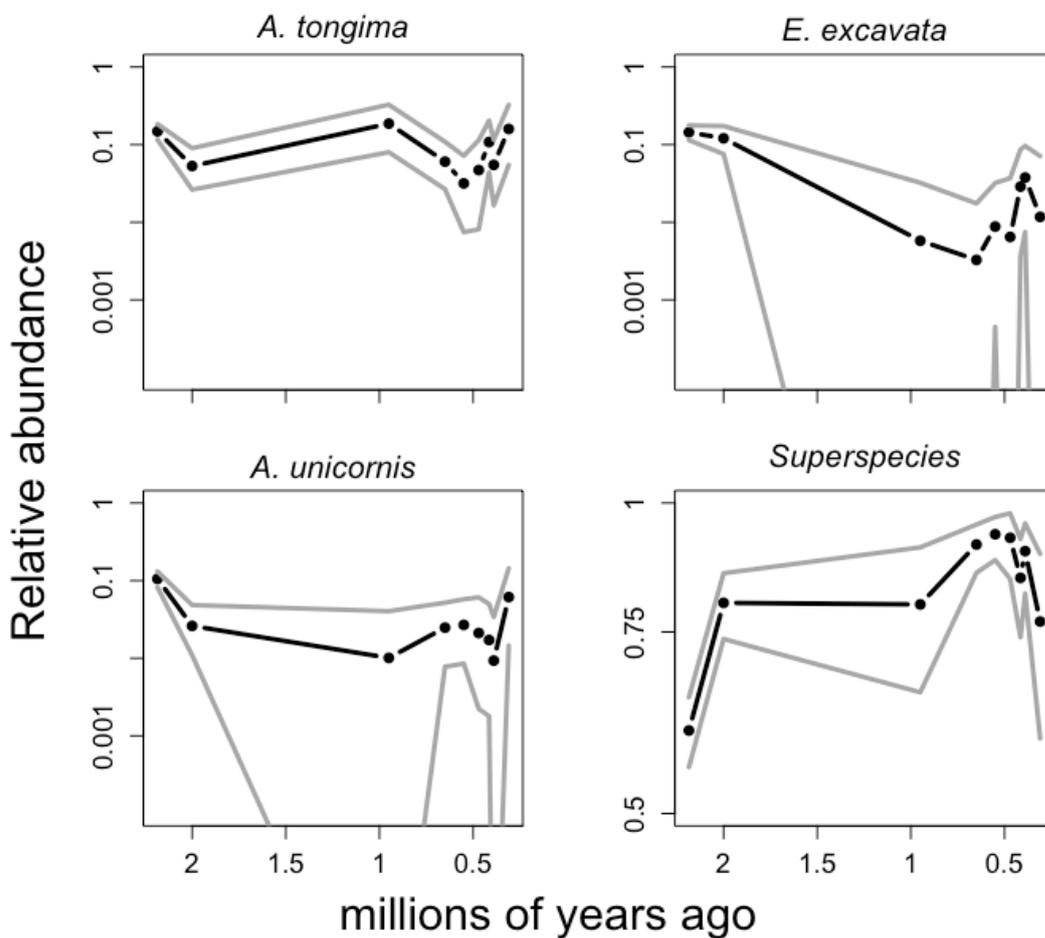
599 **Figure 4: Estimated detection probabilities.**

600



601

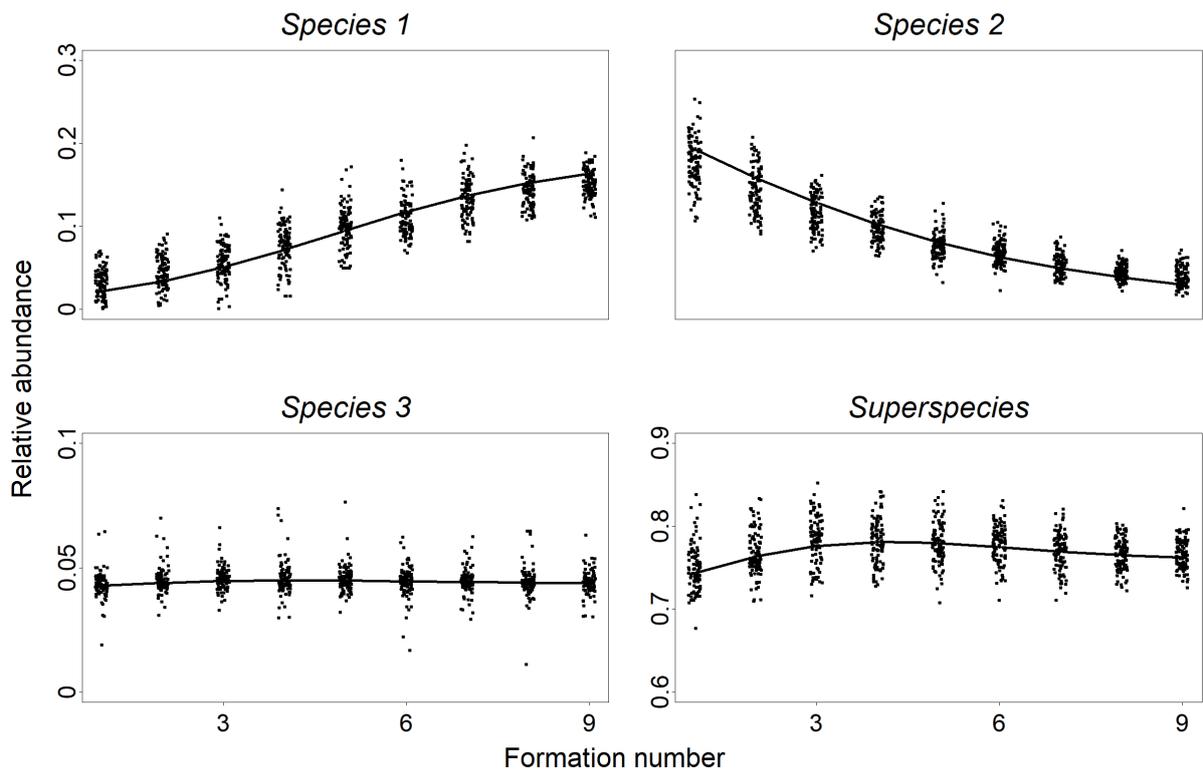
602 **Figure 5. Estimated relative abundance.**



603

604

605 **Figure 6: Relative abundances from the parameter-focused simulation study.**



606