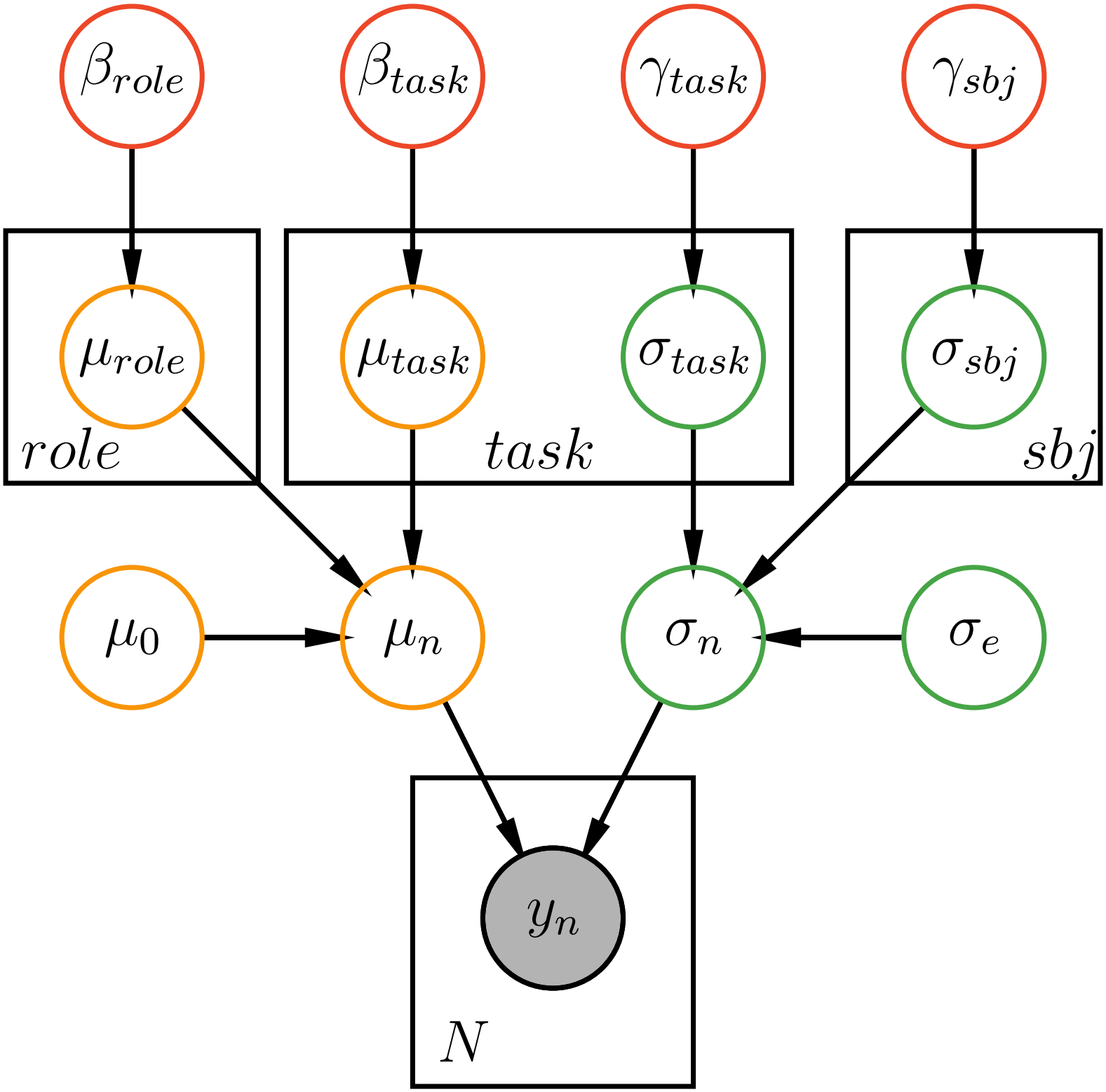
β_{role}
β_{task}
γ_{task}
γ_{sbj}
μ_{role}
μ_{task}
σ_{task}
σ_{sbj}
role
task
sbj
μ_0
μ_n
σ_n
σ_e
y_n
N